



National Technical University of Athens
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PREDICTION OF CAPSIZE PROBABILITY

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Open Workshop on Risk-Based Approaches
in the Maritime Industry

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- Related SAFEDOR Tasks:
- Environmental data
 - Probabilistic assessment of intact stability
 - Implementation

Objective:

To develop a method that:

- has a scientific basis and is capable to address individually all known types of ship instability,
- can exploit the state-of-the-art of sea wave statistics and models,
- is not biased towards a single type modeller of ship motions,
- is easily integrated within a risk assessment framework.
- practicality is demonstrable.

Key observations driving the approach:

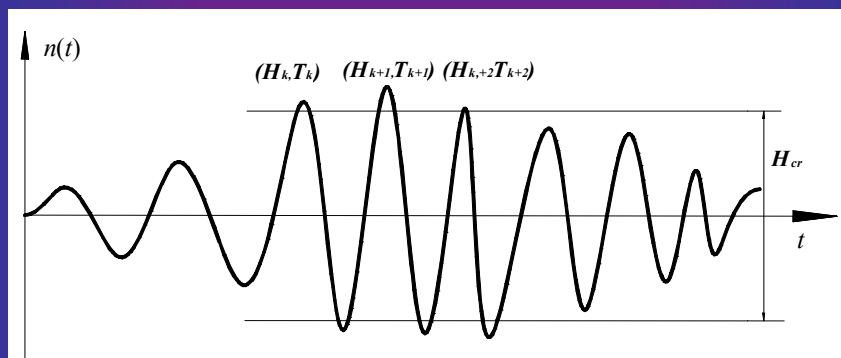
- “Near regularity” of (wave) excitation is conducive to large response.
- Ship instabilities are either:
 - manifestations of resonant behaviour (thus entailing some regularity in the excitation).
 - outcome of a single critical encounter.
 - cumulative effect of random waves.
- Higher waves tend to appear in **groups**.



- Draper (1971)
- Kimura (1980)
- Wist, Myrhaug & Rue (2004)

- Tikka & Paulling (1990)
- Myrhaug, Dahle, Rue & Slaatelid (1999)

Wave group: A sequence of waves with heights that exceed a certain preset level and nearly equal periods.
(e.g. Masson & Chandler, 1993; Ochi, 1998)



$$T_k, T_{k+1}, T_{k+2} \in [T, T + \delta T] \text{ and } H_k, H_{k+1}, H_{k+2} \geq H_{cr} \text{ (run length = 3)}$$

Run length: number of consecutive waves exceeding the preset level

Combining the strengths of deterministic and probabilistic viewpoints

Concept:

The probability of occurrence of a certain type of instability is equal to the probability of encountering the critical (or “worse”) wave group that generates the instability.

Key approximation:

Problem disassembled in two parts:

Dynamics (deterministic) part



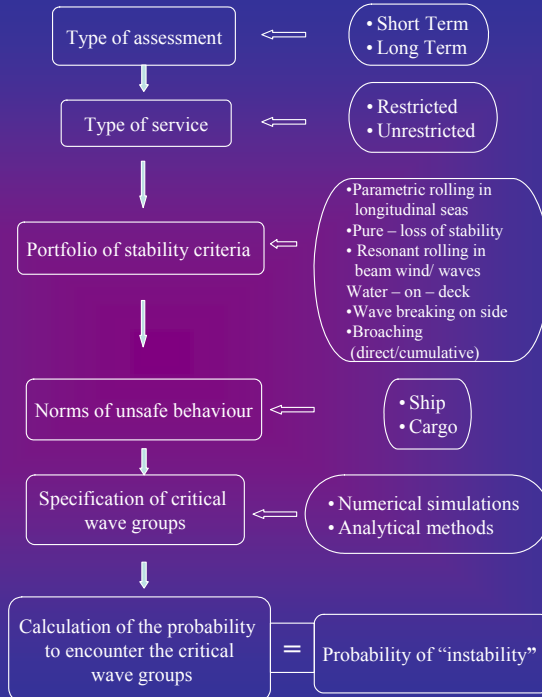
Determine specification of critical wave groups from ship motions dynamics.

Wave (probabilistic) part

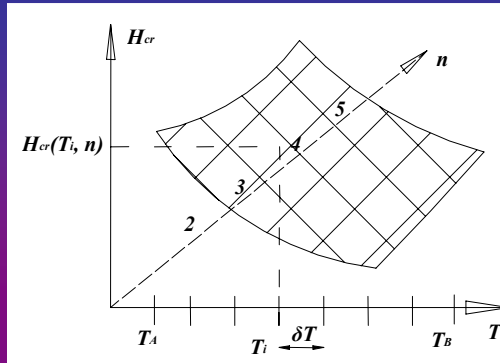


Determine probability of encounter of such wave groups from sea wave statistical models.

Flow-chart of calculation process



Procedure for determining critical wave groups.



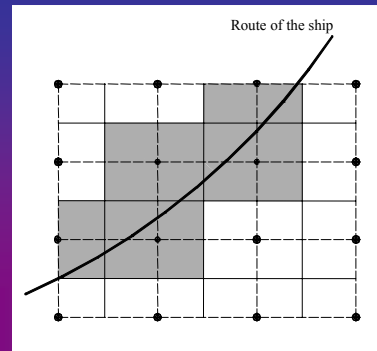
- o Discretise sea wave period range.
- o Take period T_i
- o Take n waves in group.
- o Calculate the corresponding critical wave height $H_{cr}(T_i, n)$ from ship dynamics.
- o Continue for $n+1$ waves in group.
- o Take next wave period $T_{i+1} = T_i + \delta T$ until whole range is spanned.

Distribution of "weather nodes" along route or in wider area of navigation.

Each node represents a sea-state that holds for the rectangle around the node.

Probabilities are calculated per node.

Weighted sums (according to time spent in vicinity of node) produce the overall probability figure.



Assumptions:

Gaussian waves defining a stationary ergodic random process.

Wave spectral density 'narrow banded'.

$$P = P_1 \cdot P_2$$

$$P_1 = P[T_1, T_2, \dots, T_k / H_n > H_{cr}] = \int_{\tau_i}^{\tau_j} \dots \int_{\tau_i}^{\tau_j} f(\tau/h_n > h_{cr}) d\tau, \quad n = 1, \dots, k$$

$$P_2 = P[H_n > H_{cr}] = \int_{h_n}^{\infty} f(h) dh$$

$$\text{where } \tau = \left[\frac{T_1}{T_{mean}}, \dots, \frac{T_k}{T_{mean}} \right]^T \text{ and } \tau_i = \frac{T_i}{T_{mean}}, \tau_j = \frac{T_j}{T_{mean}}, h_n = \frac{H_n}{H_{rms}}$$

Adopted wave group theory

- Kimura theory with some modification is applied (spectral method).
- A sequence of wave heights is treated as Markov chain (nonzero correlation between consecutive waves only).

Conditional pdf of n successive wave periods given the wave height exceeds a threshold level (Wist, Myrhaug & Rue):

$$f_{T/H}(\tau/h_i > h_{cr}) = \frac{e^{-\frac{1}{2}(\tau - \mu_{\tau/h_{cr}})^T \Sigma_{\tau/h_{cr}}^{-1} (\tau - \mu_{\tau/h_{cr}})}}{(2\pi)^{n/2} |\Sigma_{\tau/h_{cr}}|^{1/2}}$$

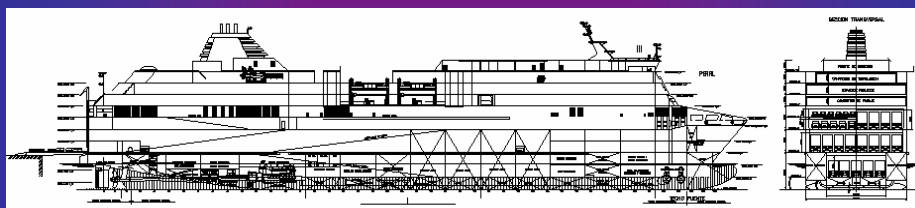
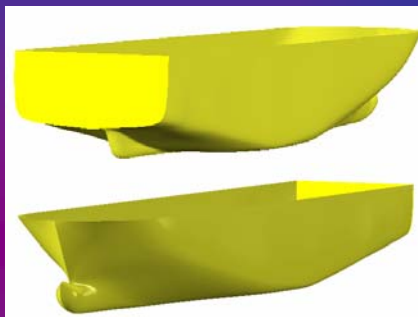
Marginal pdf for large wave heights (Tayfun):

$$f_h = \frac{h}{2[2\kappa(1+\kappa)]^{1/2}} \left(1 + \frac{1-\kappa^2}{4\kappa h^2} \right) \exp\left(-\frac{h^2}{4(1+\kappa)} \right)$$

Application 1: Ropax ferry

Ship data provided by Navantia

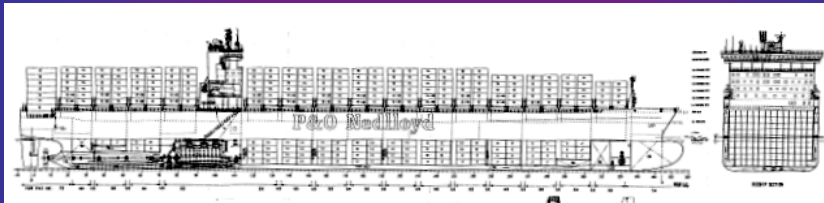
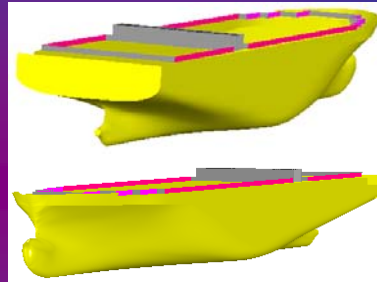
L_{bp} (length)	157 m	GM (metacentric height, corrected)	2.08 m
B (beam)	26.2 m	T_0 (natural roll period)	15.26 s
D (depth, main deck)	9.20 m	b_{BK}, l_{BK} (breadth, length of bilge keels)	0.26 m 60.9 m
T (mean draft)	6.20 m	KG (vertical position of centre of gravity above keel)	12.724 m
C_b (block coef.)	0.626	Trailers	99
V_s	22.5 kn	Cars	166



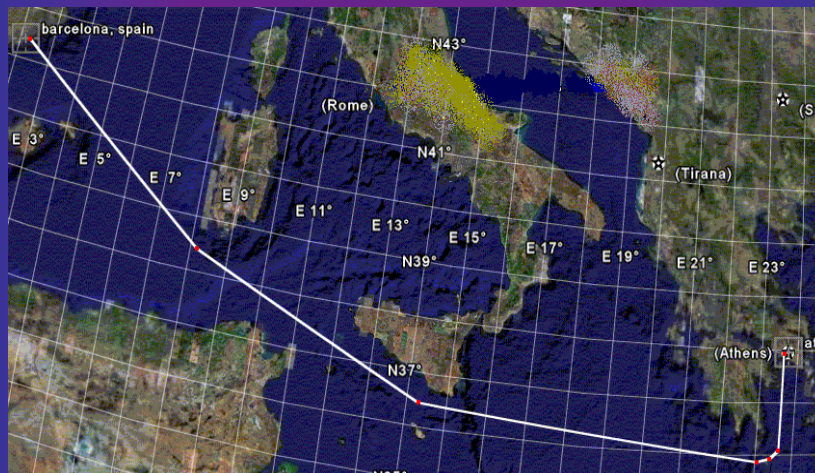
Application 2: Post – panamax containership

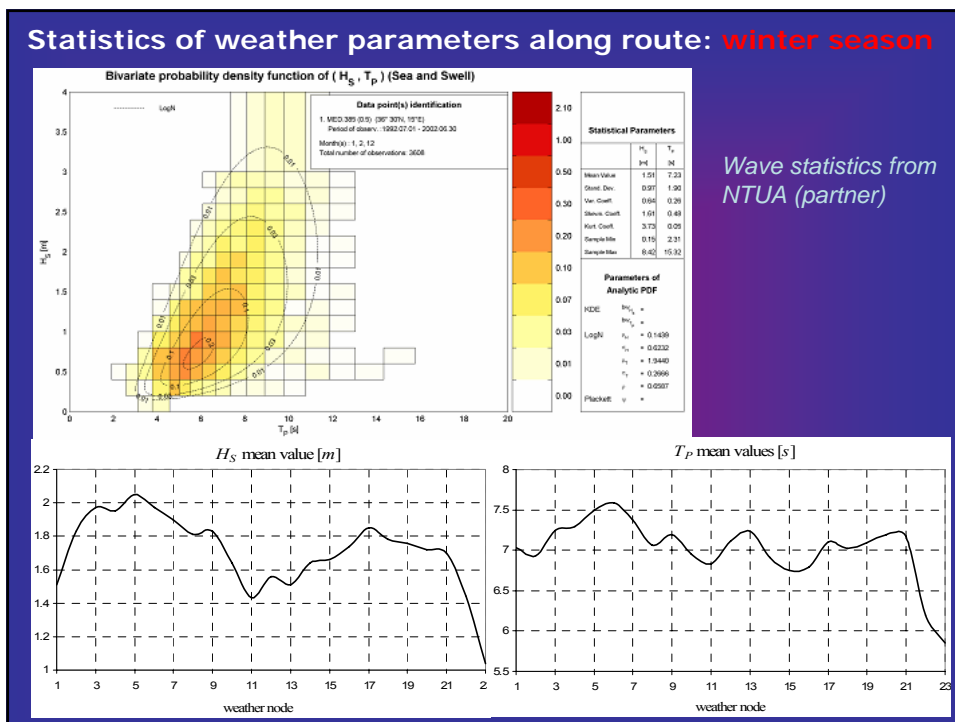
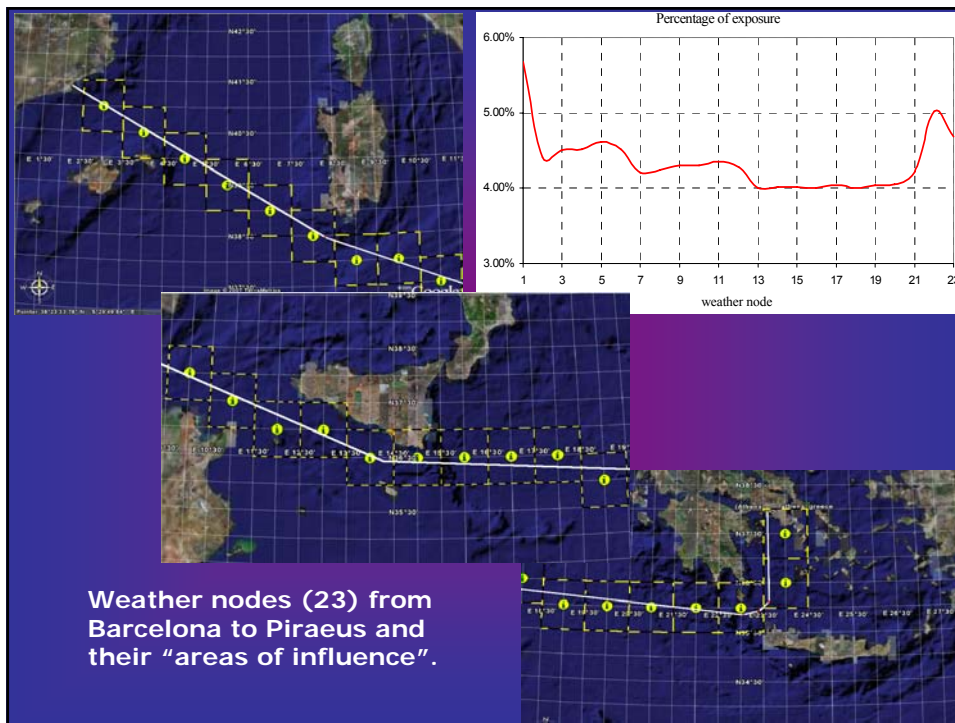
L_{bp} (length)	264.4 m	GM (metacentric height, corrected)	0.61 m
B (beam)	40 m	V_s	24 kn
D (depth, main deck)	24.3 m	T_0 (calculated natural roll period – based on roll radius of gyration $0.381B$)	39.12 s
T (mean draft)	13.97 m	KG (vertical position of centre of gravity above keel)	18.79 m
C_b (block coeff.)	0.6	number of TEUs	5048

Ship provided by GL, courtesy of Aker Yards.

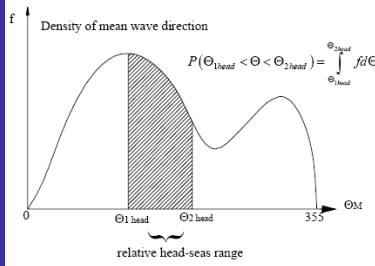
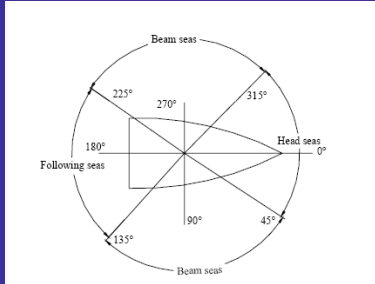


Ropax route: Barcelona – Piraeus (1209.30 n.m.)

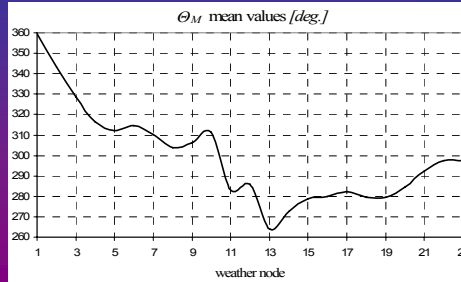




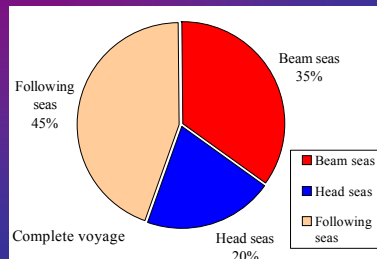
Convention of type of wave encounter
(0° waves coming from North, 90° East)



Mean wave direction per node

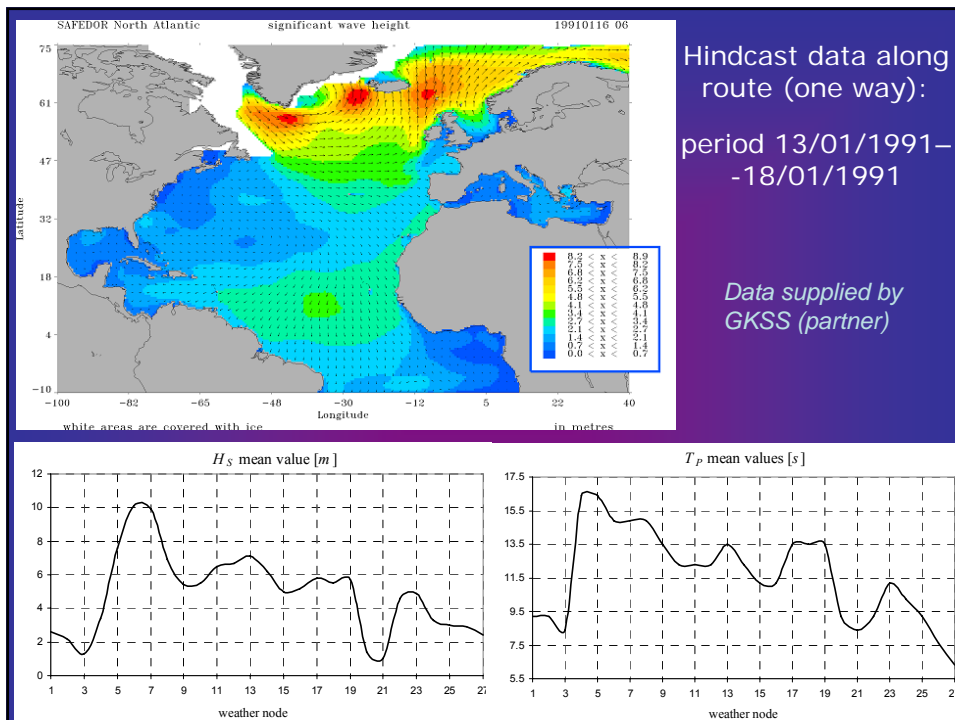
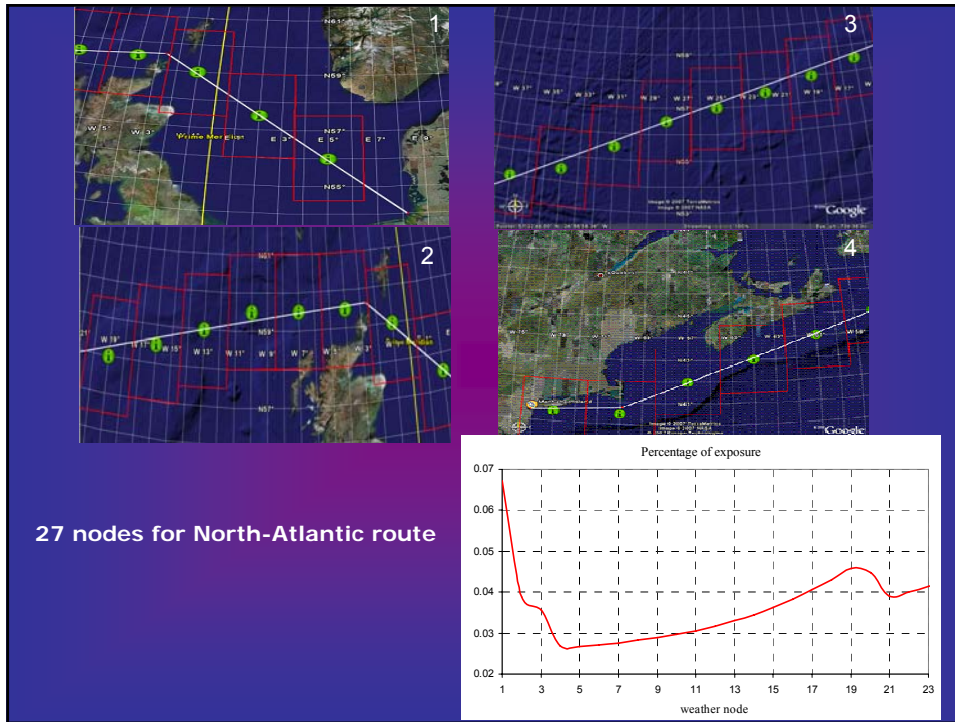


% in beam, head & following seas

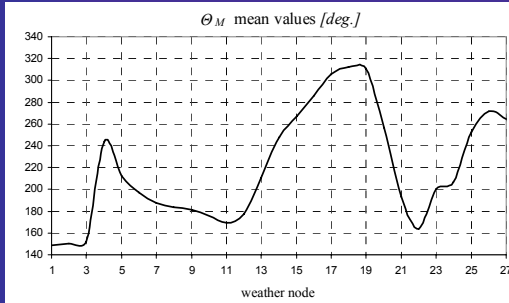


Containership route: Hamburg – New York (3422.86 n.m.)



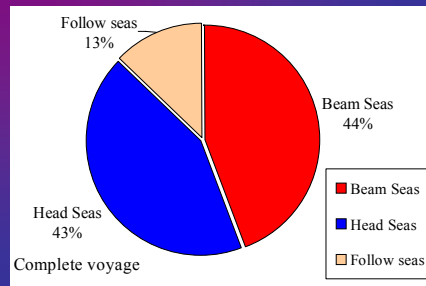


Mean wave direction per node



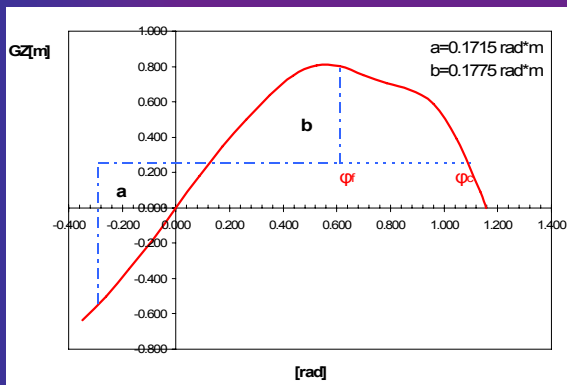
North-Atlantic route

% in beam, head & following seas



Safety limits of ROPAX

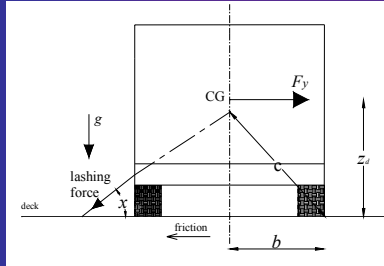
"Capsize" threshold \rightarrow Critical inclination \rightarrow Critical roll angle set according to the weather criterion, as the minor of:



- the angle of vanishing stability (63°)
- flooding of non-watertight openings (35°)
- 50 deg

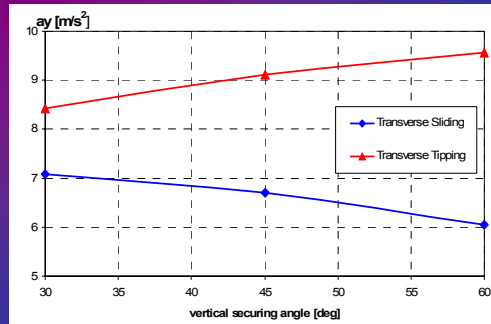
Critical roll angle 35 deg

Shift-of-cargo threshold \Rightarrow Critical transverse acceleration that could endanger the lashing of remotest trailer (against tipping and sliding) \Rightarrow Examination of lashing strength according to IMO's *Cargo Securing Manual*

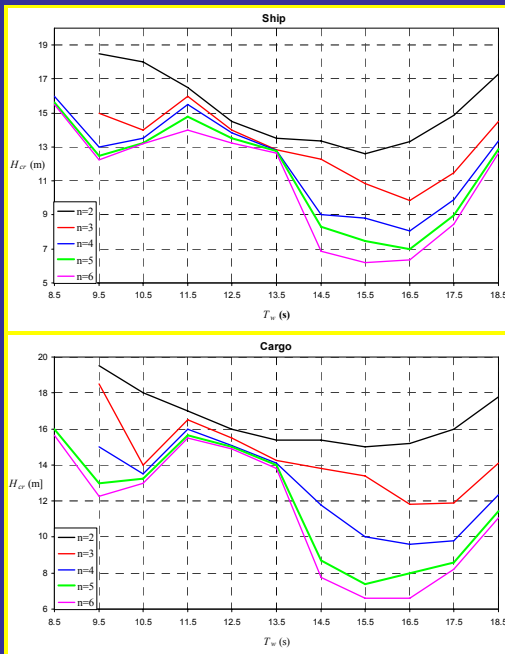


cargo mass	$m = 49 \text{ t}$
centre of gravity above deck	$a = 2.36 \text{ m}$
lever-arm of tipping	$b = 1.261 \text{ m}$
Coefficient of friction	Steel – rubber: $\mu = 0.3$
lashing arrangement	3 chains with MSL = 100 kN on each side, symmetrical vertical securing angle: $\alpha = 30^\circ/45^\circ/60^\circ$

Critical transverse acceleration = 6.04 m/s^2



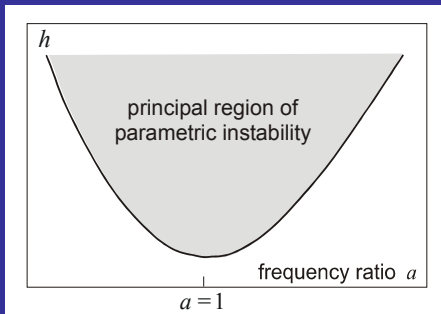
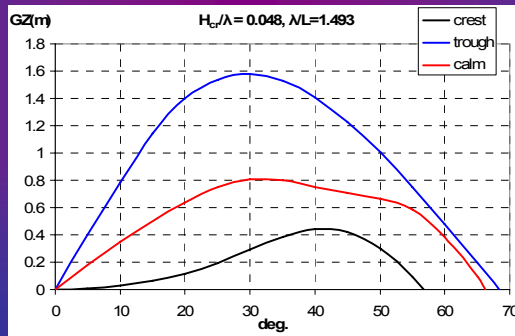
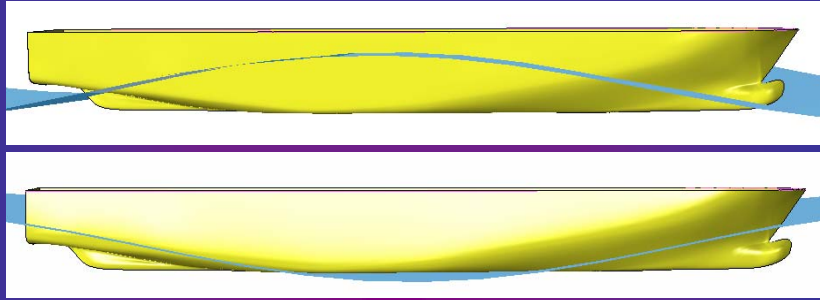
CRITICAL WAVE GROUPS (1): BEAM-SEA RESONANCE



Employed ship dynamics tool: Coupled roll, heave and sway simulation model (Themelis & Spyrou 2006).

- Ship assumed initially unbiased (no wind).
- Waves approach ship from 90°
- Wave breaking limit taken into account.

CRITICAL WAVE GROUPS (2): HEAD-SEAS PARAMETRIC ROLLING



Key parameters:

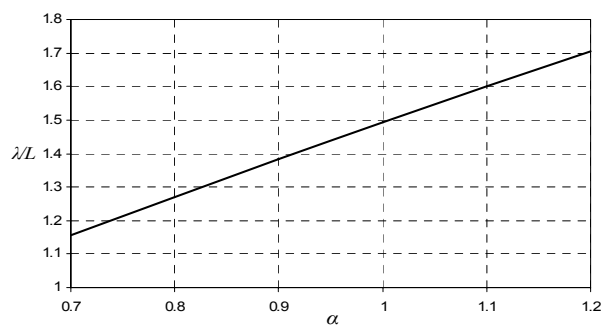
$$a = \frac{4\omega_0^2}{\omega_e^2}$$

ω_0 : natural roll frequency

ω_e : frequency of encounter

$h = f$ (GZ fluctuation on wave)

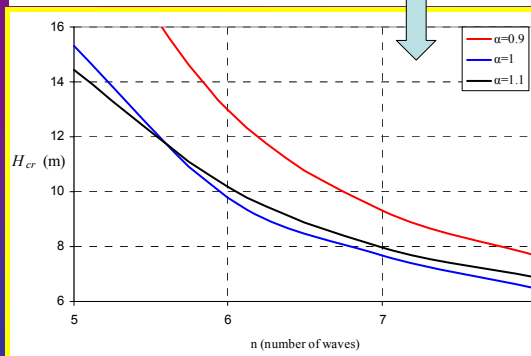
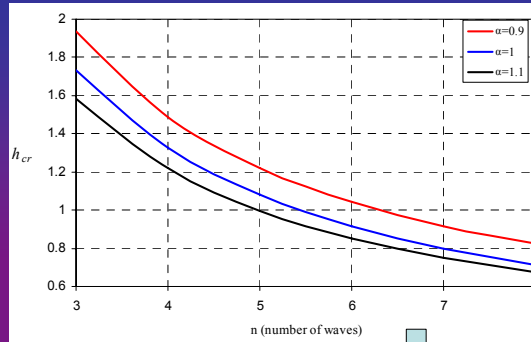
Given the speed,
find eligible range
of wave lengths.



“Transient” criterion

$$h - \frac{4k}{\omega_0} = \frac{0.693 + \ln q}{1.571p}$$

Critical wave heights, depending on number of waves in group:



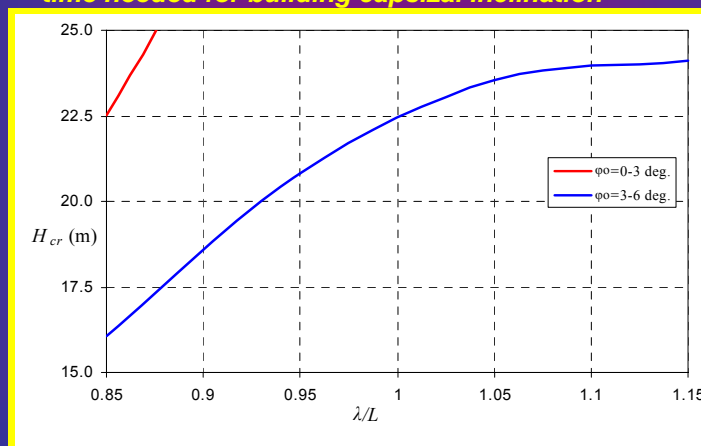
CRITICAL WAVE GROUPS (3): PURE-LOSS-OF-STABILITY (FOLLOWING SEAS)

Key condition:

time with negative restoring in the vicinity of crest

greater than

time needed for building capsizal inclination



CALCULATION OF PROBABILITIES

Mean seasonal (winter) values of wave parameters considered.

JONSWAP spectrum assumed for sea waves.

Encounter wave spectrum taken into account.

Probabilities expressed as percentage of critical time t_i scaled with respect to the time of exposure:

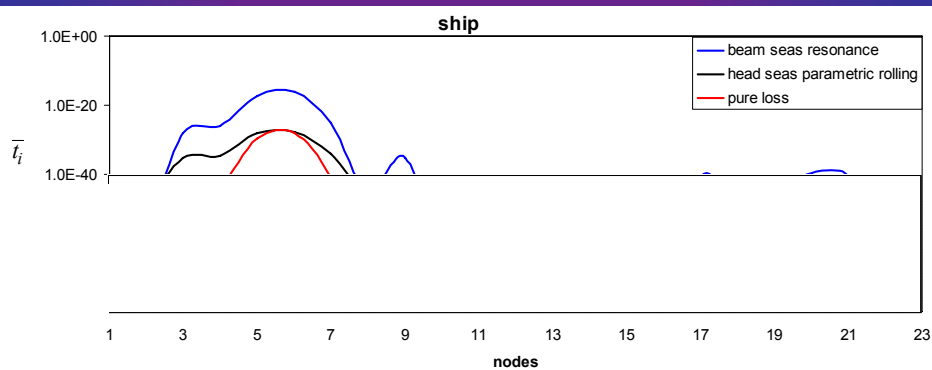
$$\bar{t}_i = \frac{t_i}{t_{tot}} = P_i \frac{T_i}{T_m}$$

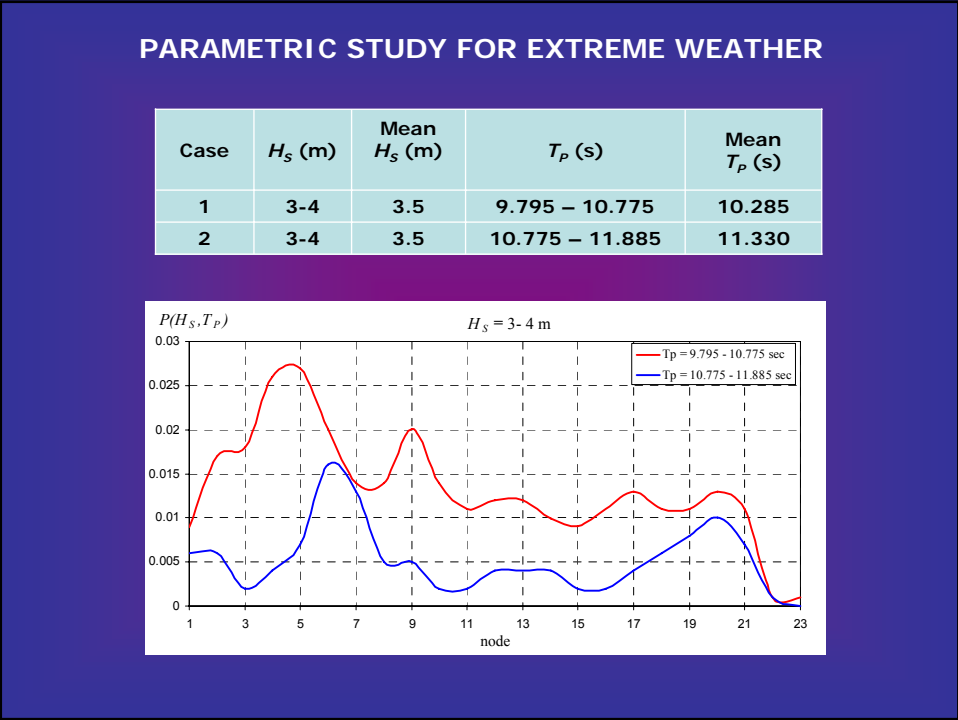
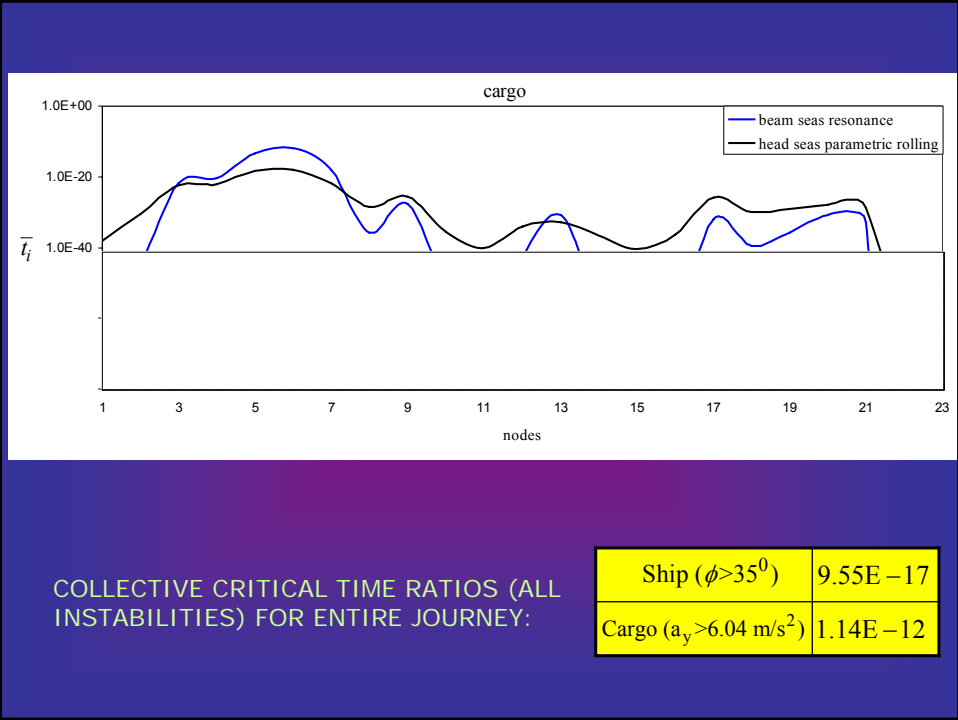
P_i = probability of a wave group i having wave period around T_i .

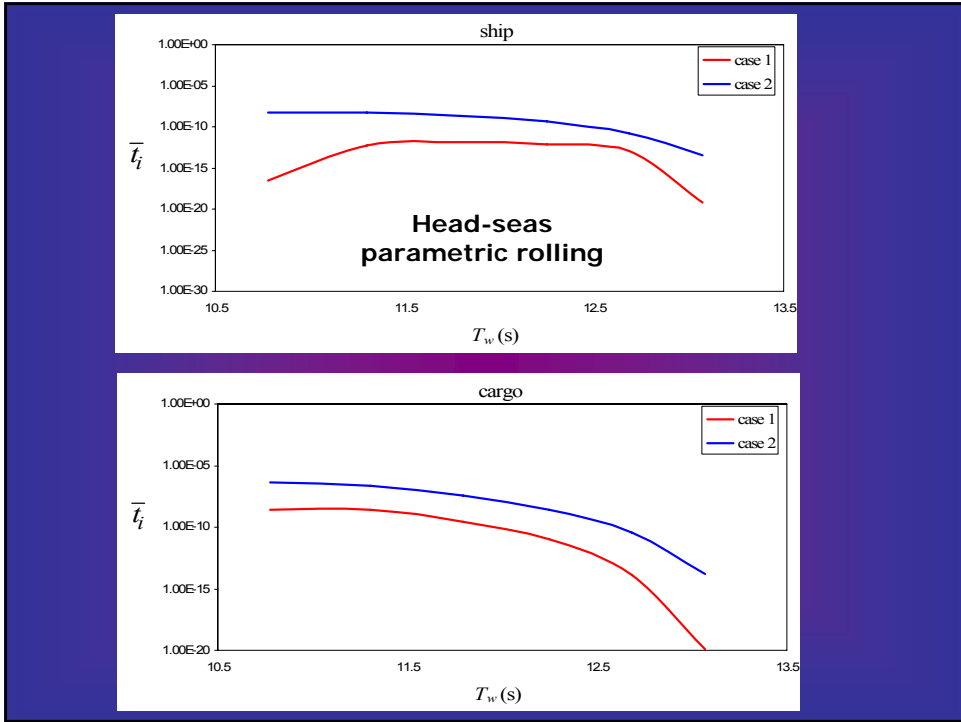
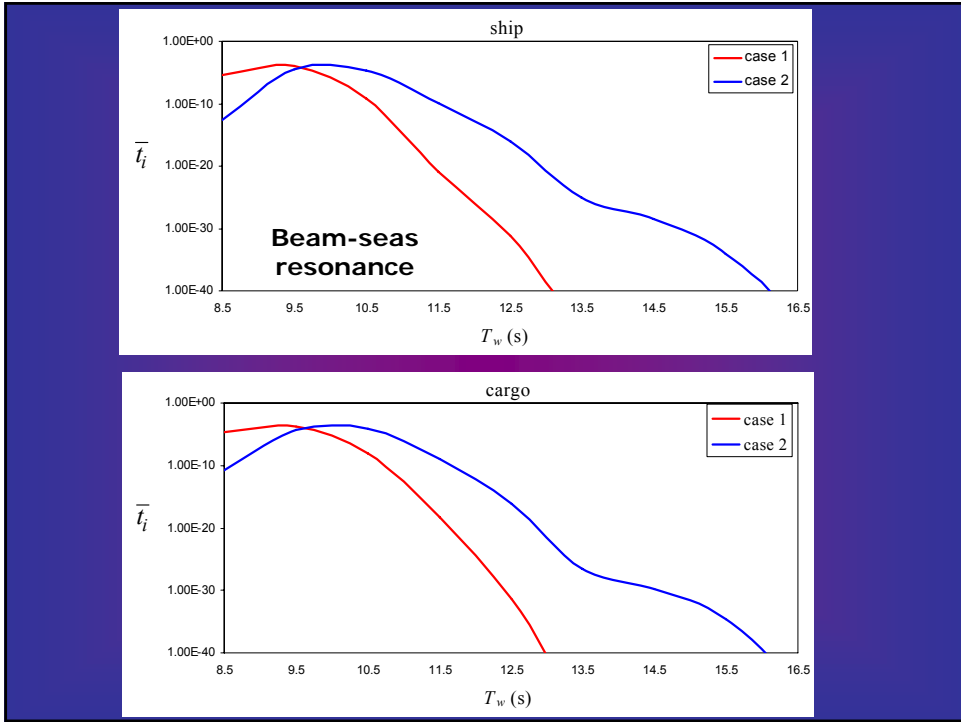
t_{tot} = duration of the part of the voyage inside the influence area of the considered node.

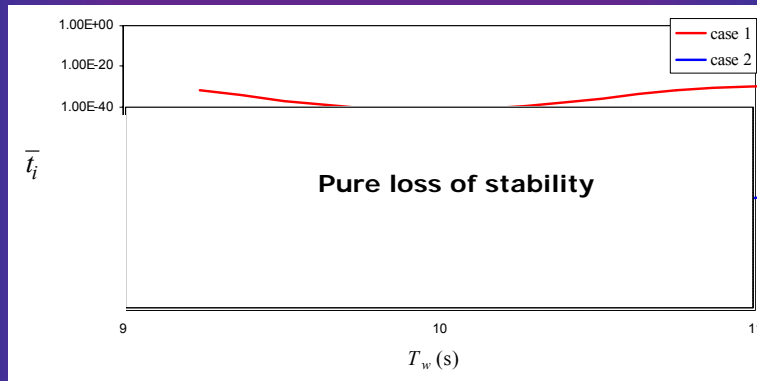
T_m = mean wave period associated with the weather node.

"CRITICAL TIME RATIO" ALONG ROUTE PER TYPE OF INSTABILITY









Critical time ratios (overall) for extreme weather

	Case 1	Case 2
Ship ($\phi > 35^\circ$)	3.55E-5	2.12E-5
Cargo ($a_y > 6.04 \text{ m/s}^2$)	7.60E-5	4.08E-5

CONCLUDING REMARKS

- A practical probabilistic stability assessment method that is embeddable upon a "risk-based" framework of assessment has been developed during the SAFEDOR project.

- It was succeeded to exploit the strength of deterministic approach and to provide a bridge with state-of-the-art wave/wind models.

- The feasibility of the method was shown through application to a Ropax ferry that was assessed for operation on a specific route across the Mediterranean Sea. A further study for a containership is nearing completion.