

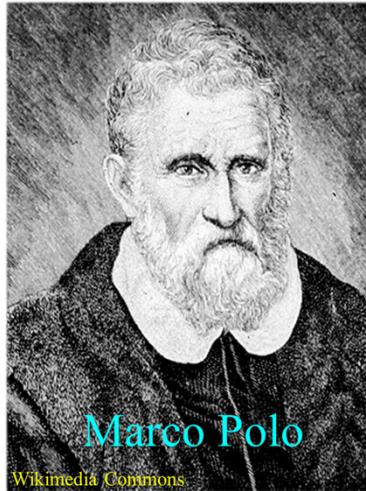
複数AUVと洋上中継器で構成した純無人型 探査ユニットによる海底熱水地帯の潜航調査

Near-Bottom Survey of a Hydrothermal Vent Site by Deploying an
Unmanned Exploration Unit of ASV-Controlled Multiple AUVs

金岡秀

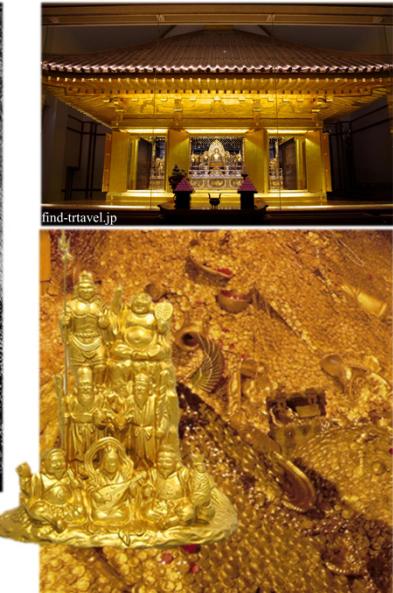
AUV開発研究グループ
海洋利用水中技術系 海上技術安全研究所
国立研究開発法人 海上・港湾・航空技術研究所

Zipangu: Land of Gold



Marco Polo

Wikimedia Commons



find-trtravel.jp

"People on the Island of Zipangu (Japan) have tremendous quantities of gold. The King's palace is roofed with pure gold, and his floors are paved in gold two fingers thick." -

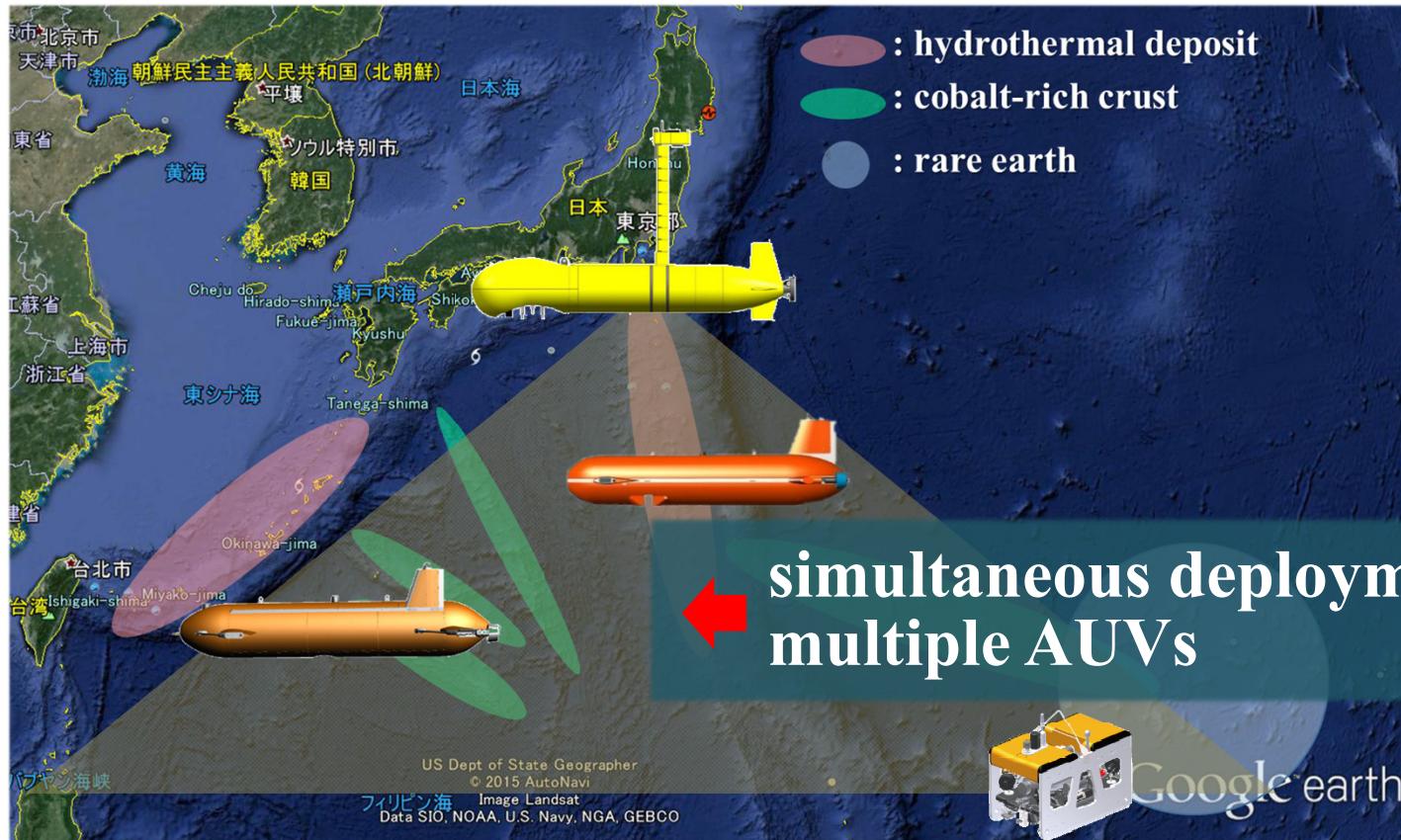
The Travels of Marco Polo

(13th century)



Searching for the Zipangu in the Sea

▪ Seabed Mineral Resources



* Source: Japan Project-Industry Council

estimated deposit	available	value
hydrothermal deposit	750×10^6 ton	0.67 trillion USD
cobalt-rich crust	2.4×10^9 ton	0.83 trillion USD

cf.) Japan's GDP in 2016: 4.73 trillion USD (IMF)



The Lineup

- NMRI's AUVs and an ASV

Hobalin

Date of Birth : 19th Nov., 2015

(Scorpio)



Jun. 2016 Jul. 2016 Sep. 2016 Oct. 2016 Nov. 2016 Dec. 2016

Okhotsk Sea Okinawa Trough Suruga Bay Omuro Okinawa Trough

Suruga Bay Hobalin + 1 ASV Caldron Trough



Omuro Caldron
Simultaneous Deployment of
3 AUVs + 1 ASV

C-AUV #01

Date of Birth :

8th Dec., 2015 (Sagittarius)

Suruga Bay
Launch & Sea Trial



Sep. 2016

Suruga Bay
Simultaneous Deployment of
2 AUVs + 1 ASV

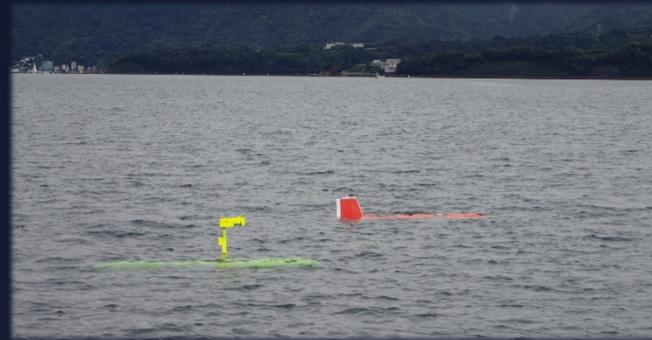
Dec. 2016



- NMRI's AUVs and an ASV

- ▲ C-AUV #02

Date of Birth :
20th Jul., 2016 (Cancer)



Sep. 2016

Suruga Bay
Simultaneous Deployment of
2 AUVs + 1 ASV

Dec. 2016

- ▲ ASV for AUV control

Date of Birth :

12th Sep., 2016 (Virgo)



Sep. 2016

Suruga Bay
Simultaneous Deployment of
2 AUVs + 1 ASV

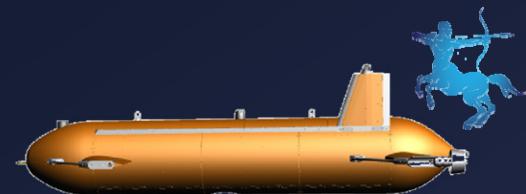
Dec. 2016



▪ Specifications and Payloads



	dimensions (m)	mass (kg)	depth rating (m)	speed (m/s)	main payload
C-AUV #01	3.9×0.65	780	2000	1.5	PSBP
C-AUV #02	3.6×0.6	620	2000	1.5	MBES
Hobalin	1.2×0.7×0.76	270	2000	0.4	camera
ASV for AUV control	4.0×0.58	800	-	1.5	-



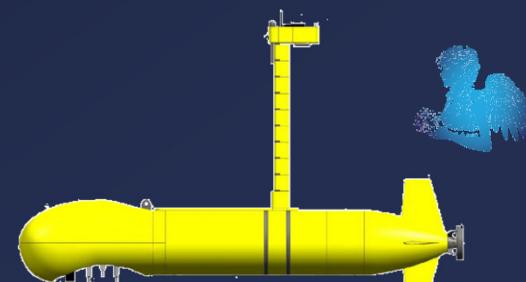
C-AUV #01



C-AUV #02



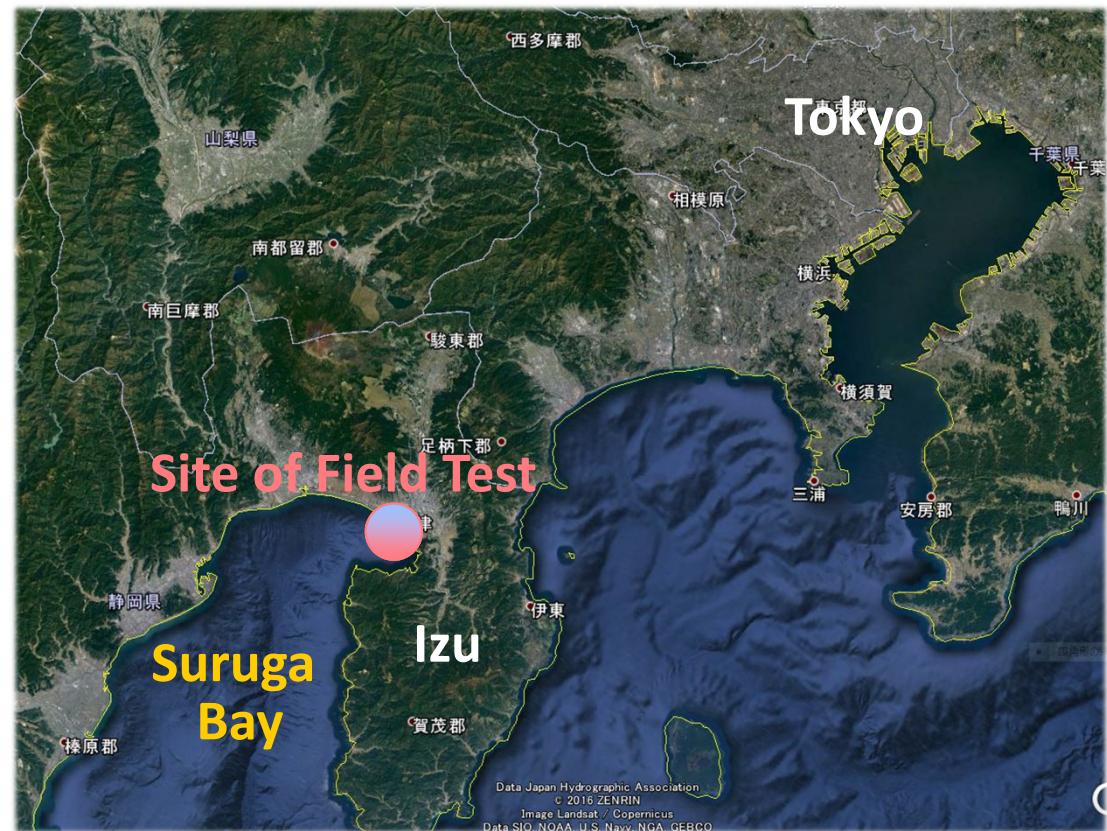
Hobalin



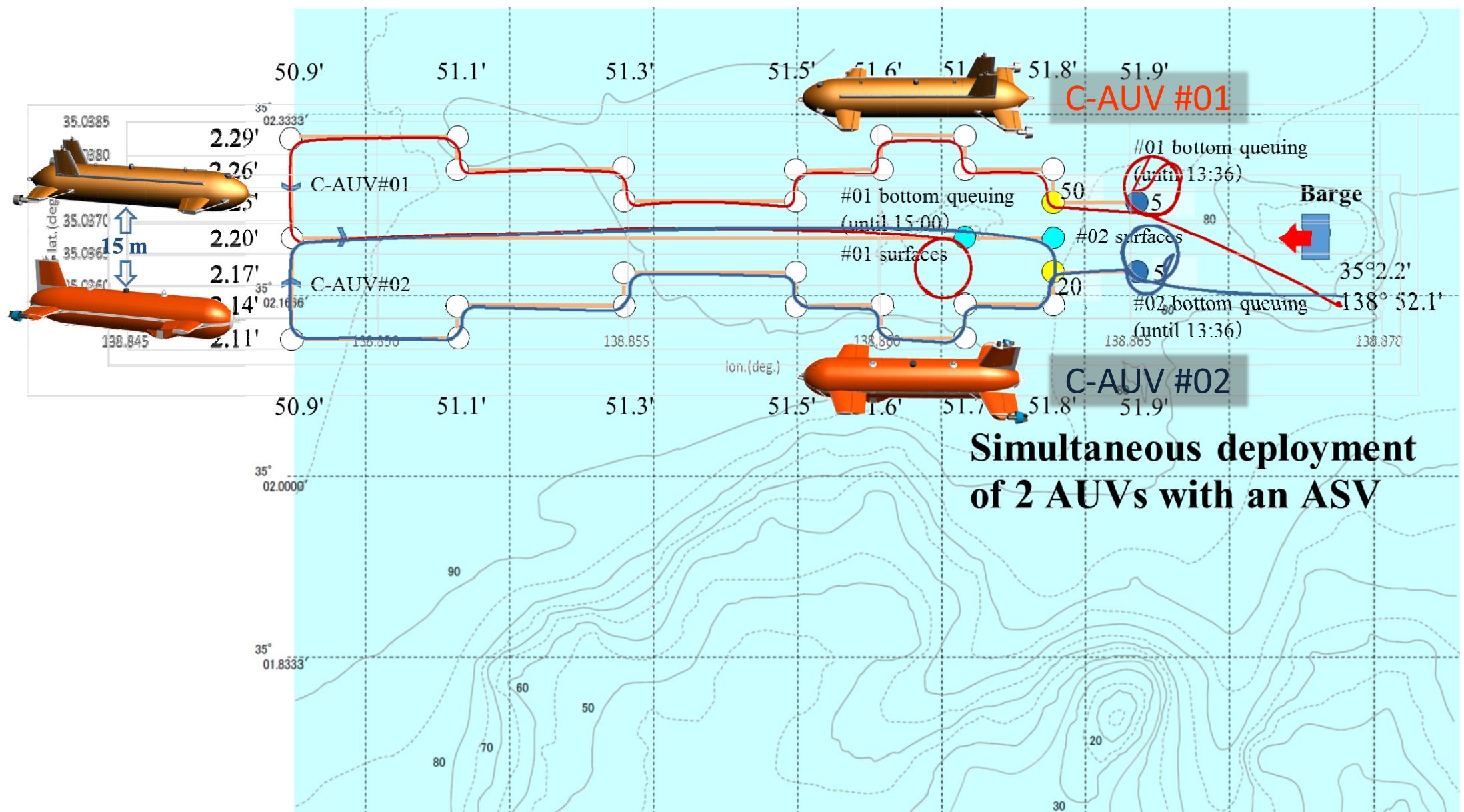
ASV for AUV control

Field Test in Suruga Bay

- 2 C-AUVs surveilled by ASV
- A semi-practical bottom survey dive

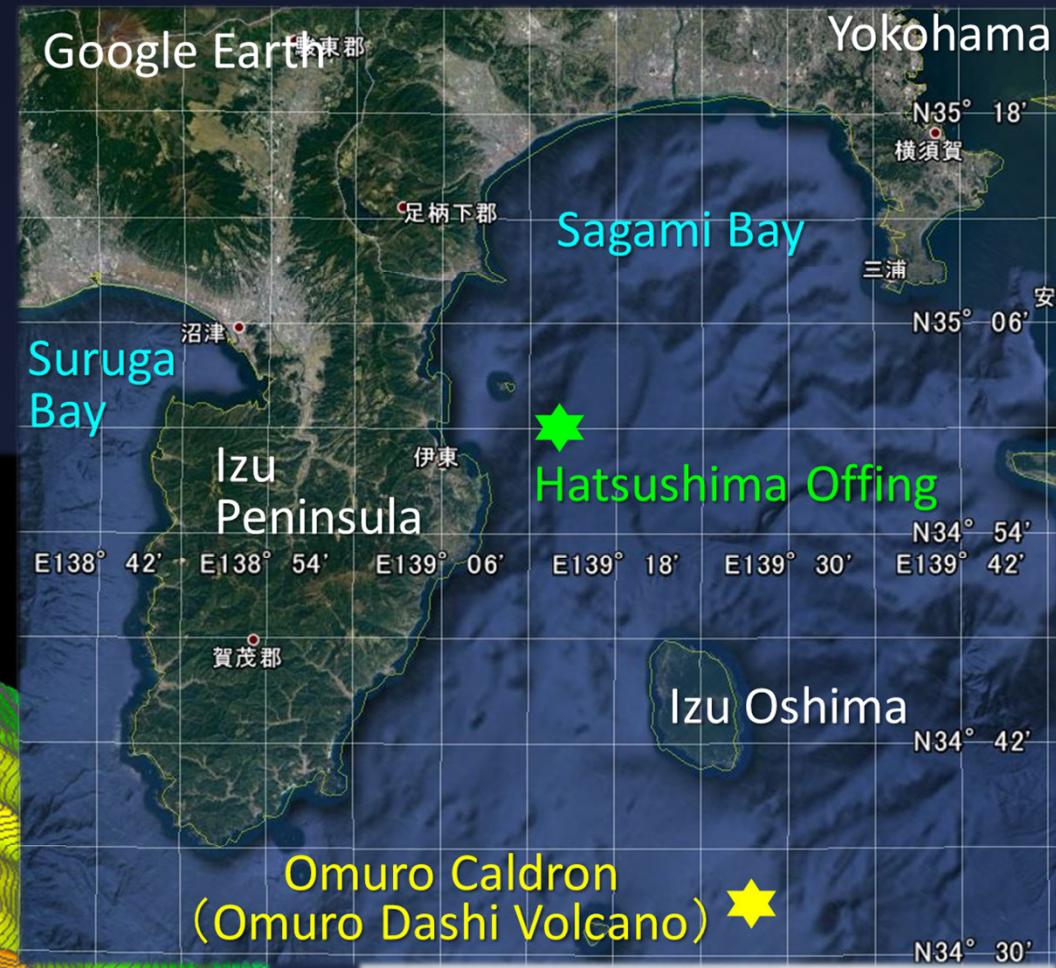
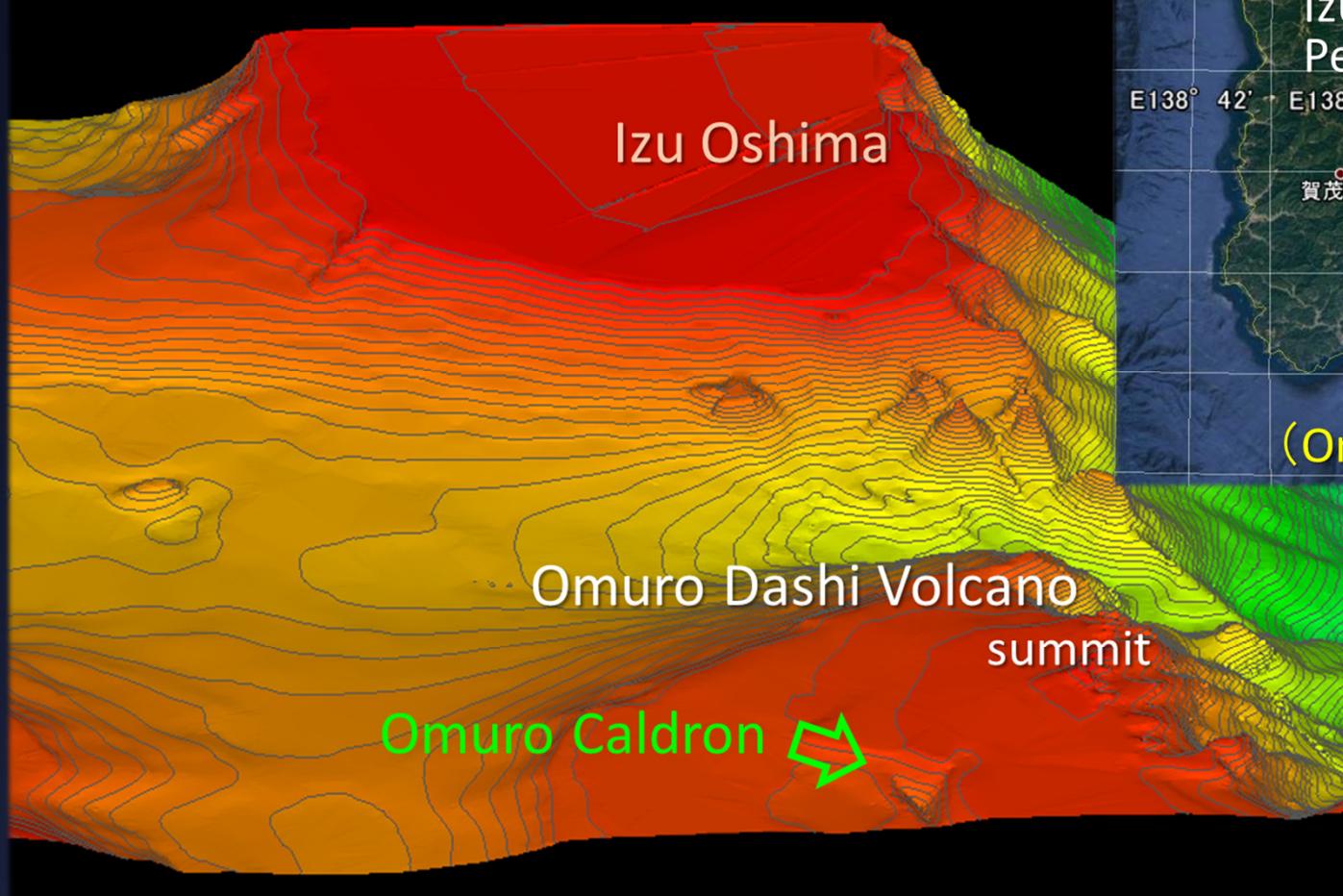


Navigation and Dive Results

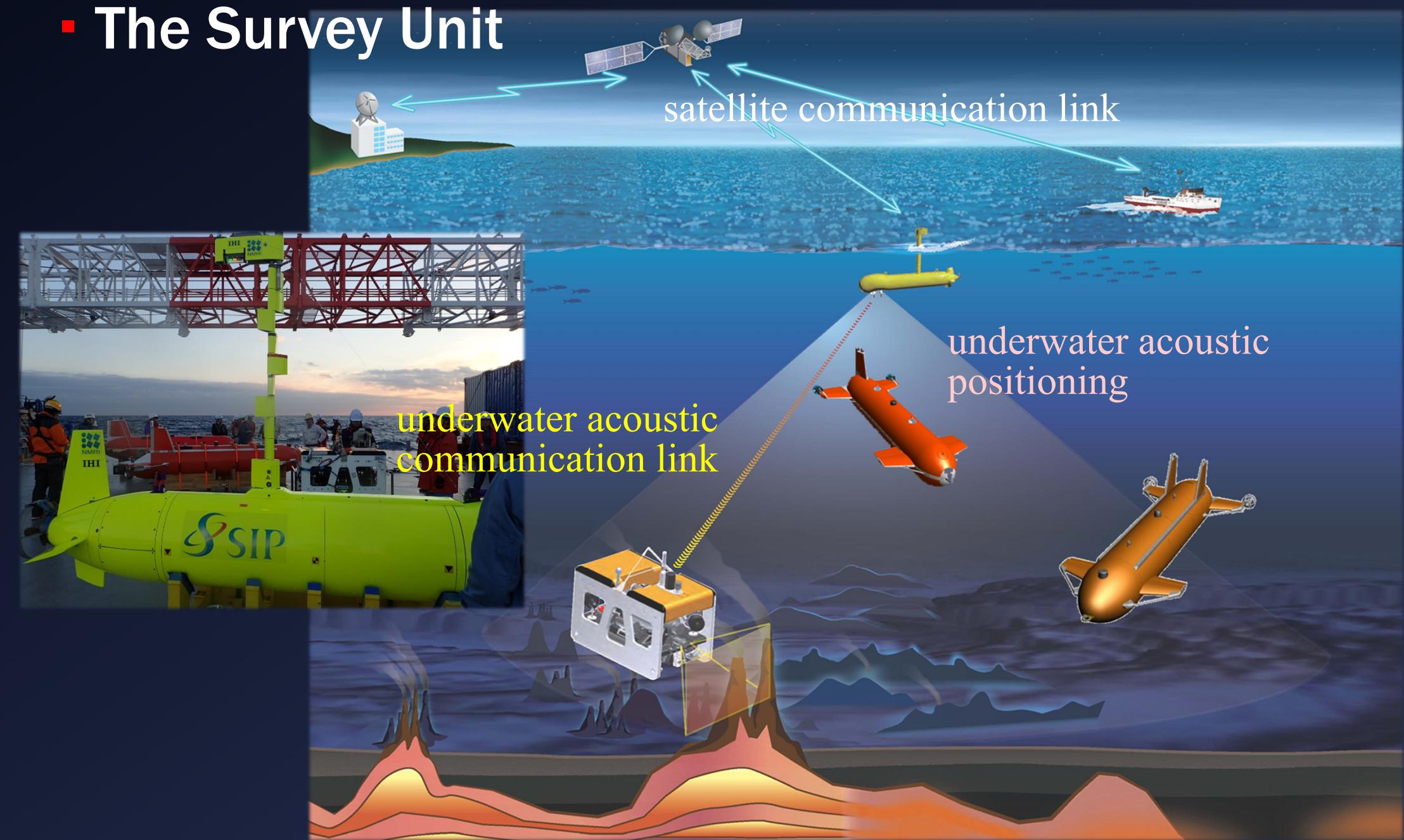


Survey Cruise

- AUGUST 1100-16306 Cruise
Hydrothermal Activity Survey in Omuro Calderon
- Nov. 28 - Dec. 4, 2016

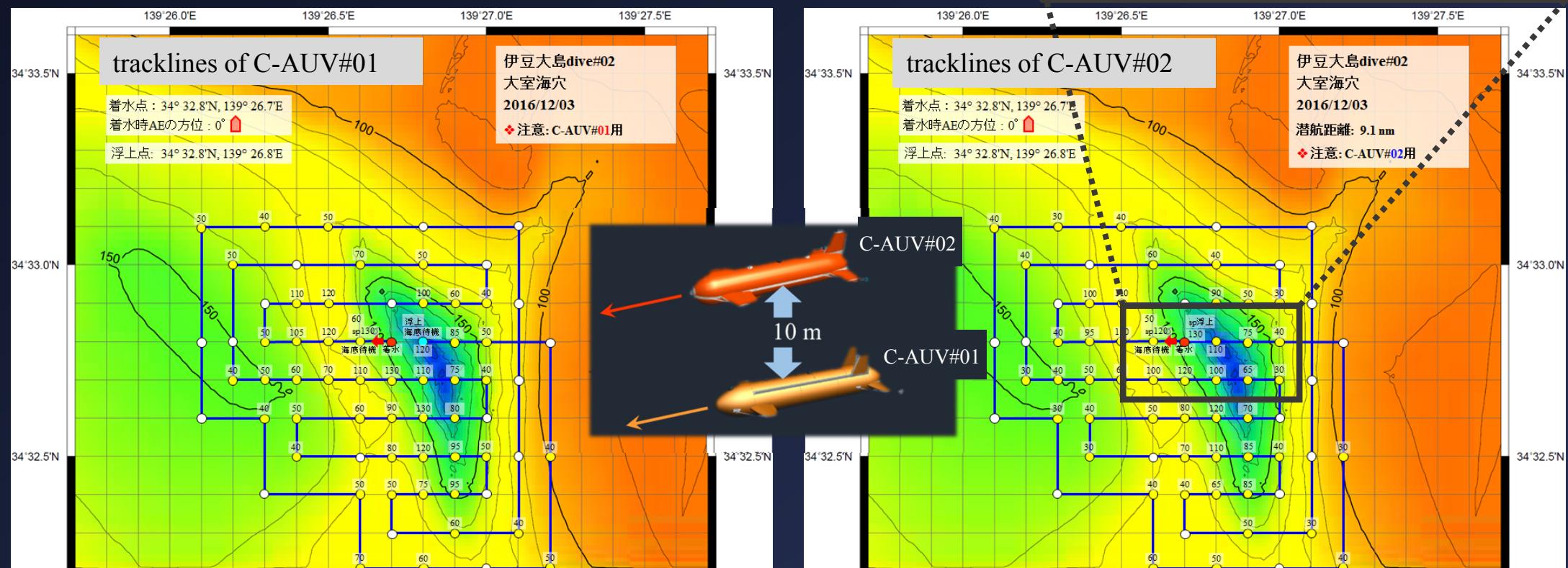
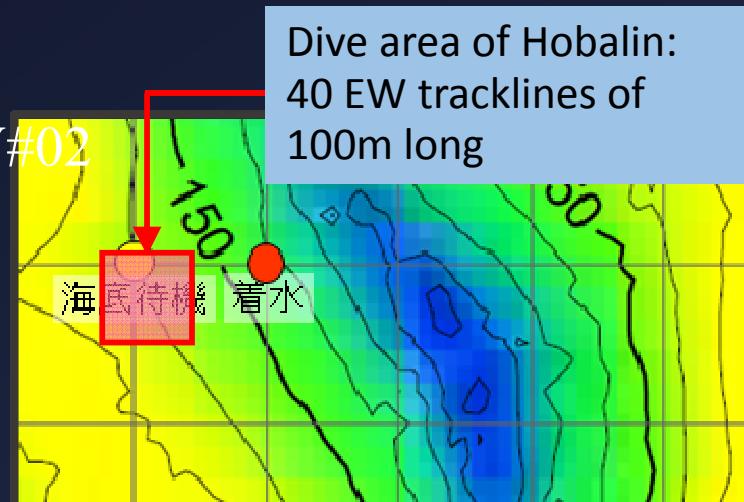


The Survey Unit

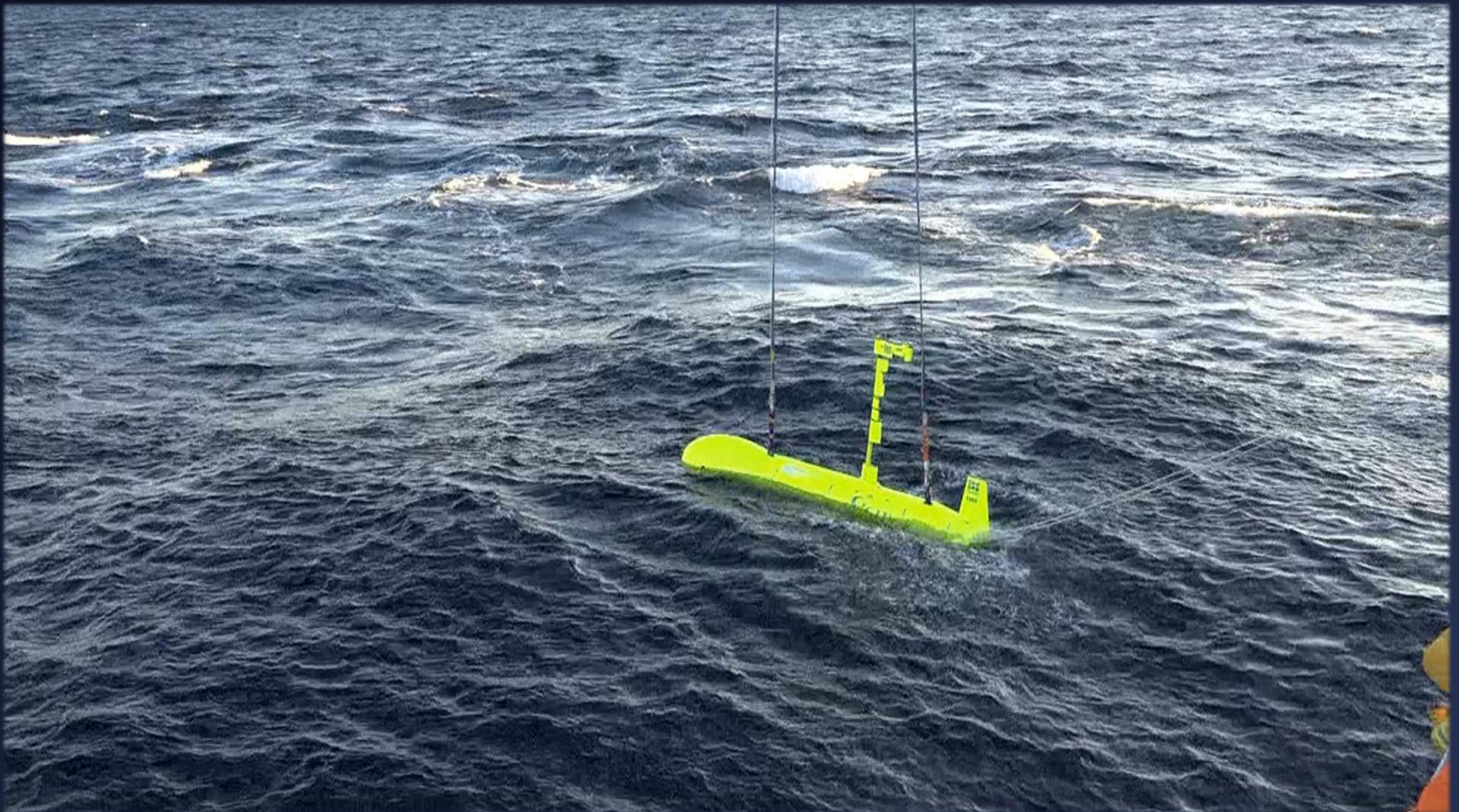


▪ Navigation

- Order of Deployment: ASV, Hobalin, C-AUV#01, C-AUV#02
- Simultaneous Start of Bottom Tracking: C-AUV #01 & 02
- Sequential Surfacing of 3 AUVs

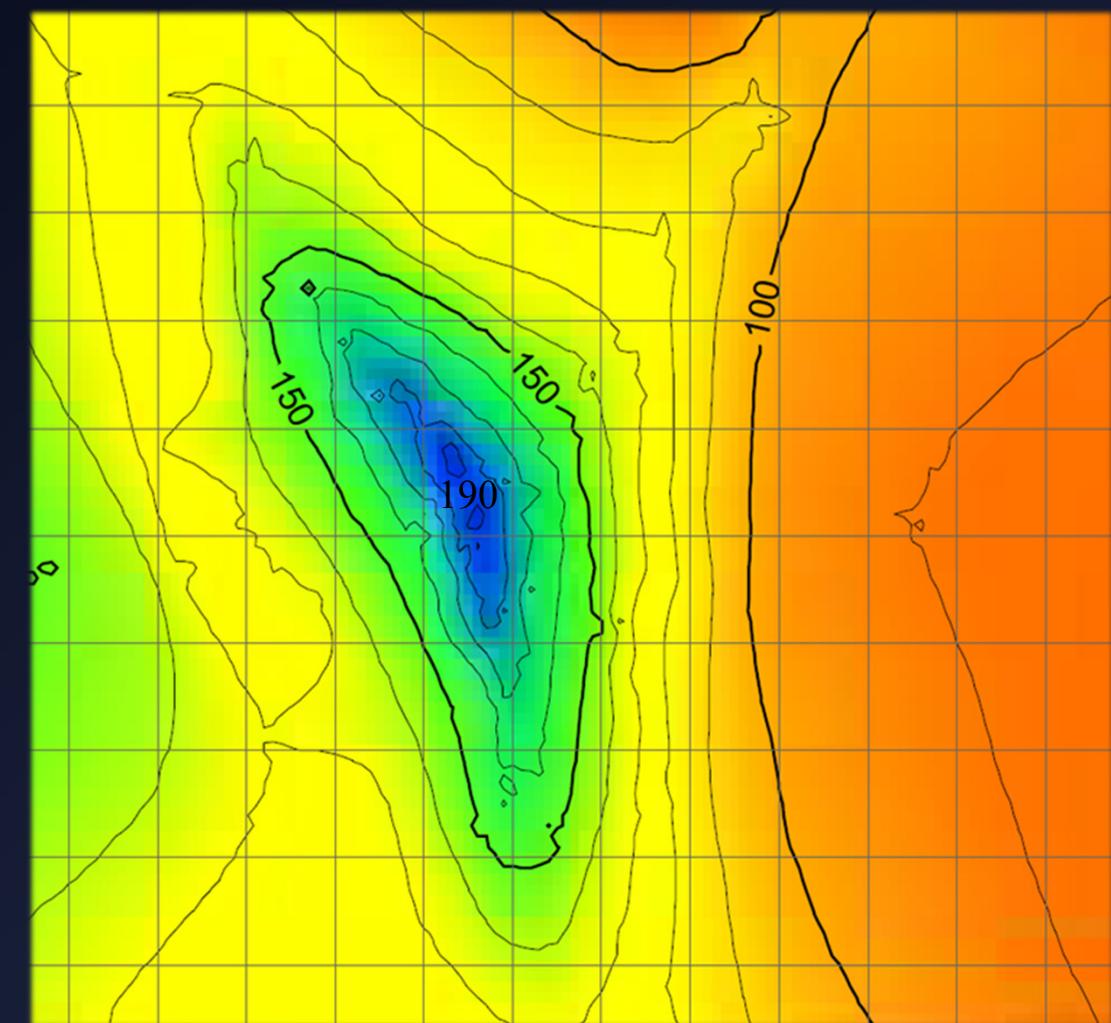


▪ Scenes of Survey Works

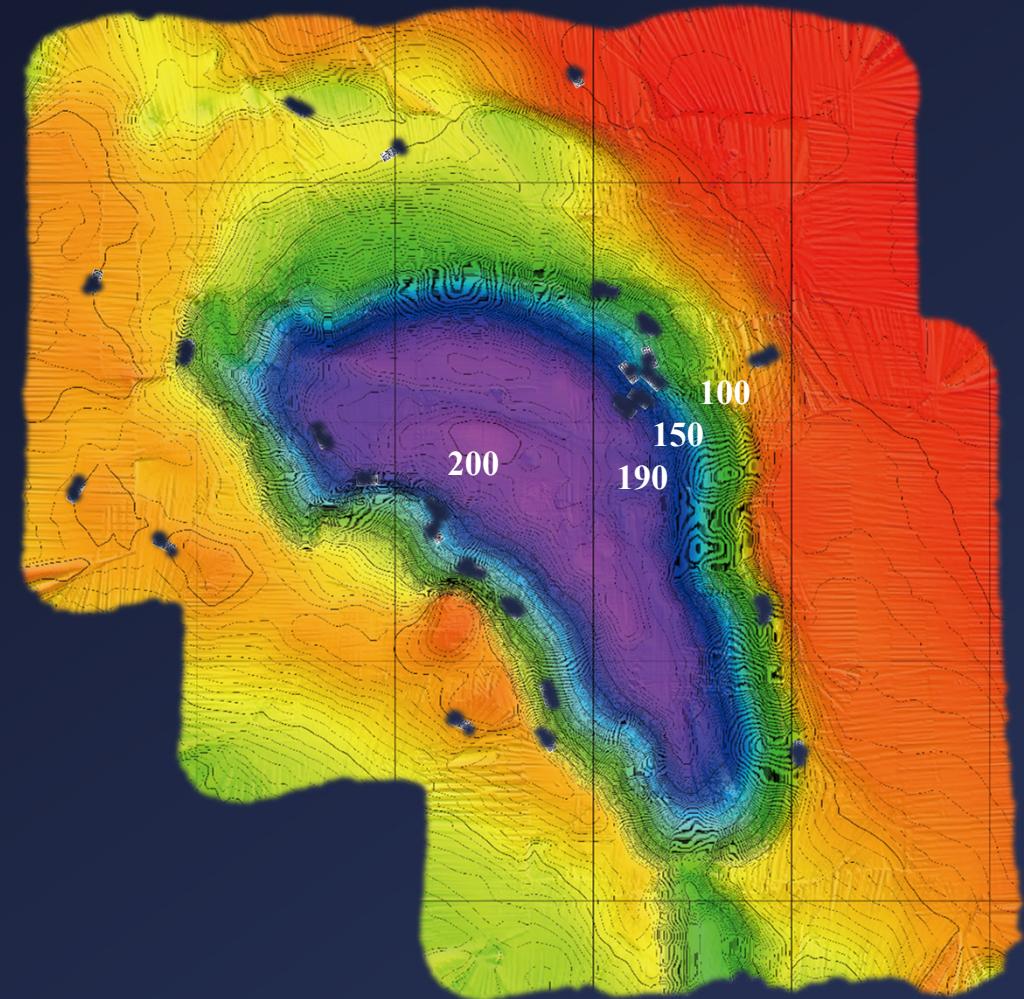


Survey Results

- Bottom Bathymetry

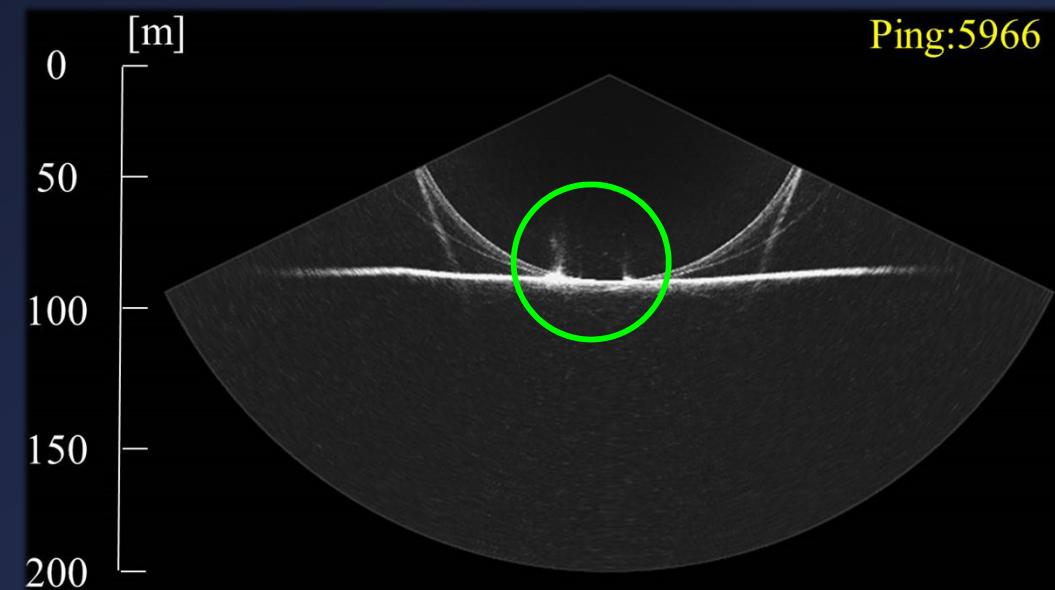
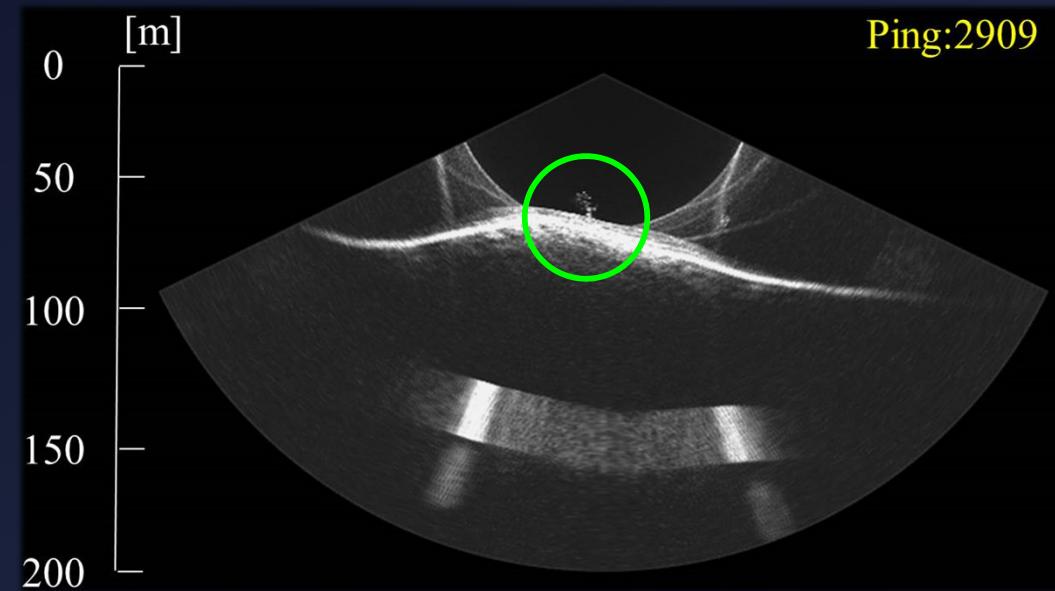
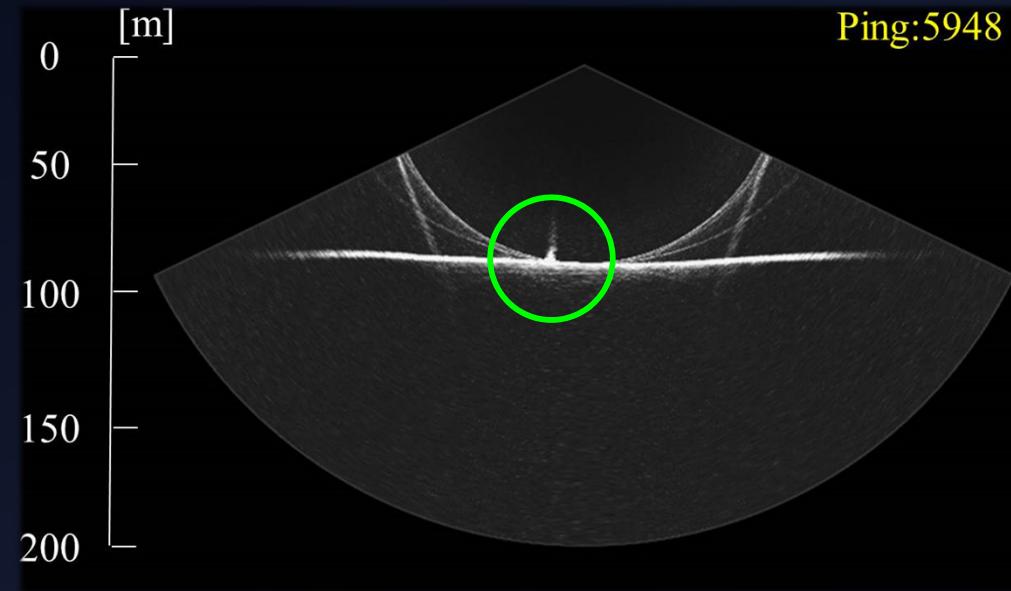


existing: 50 m meshed, surface vessel

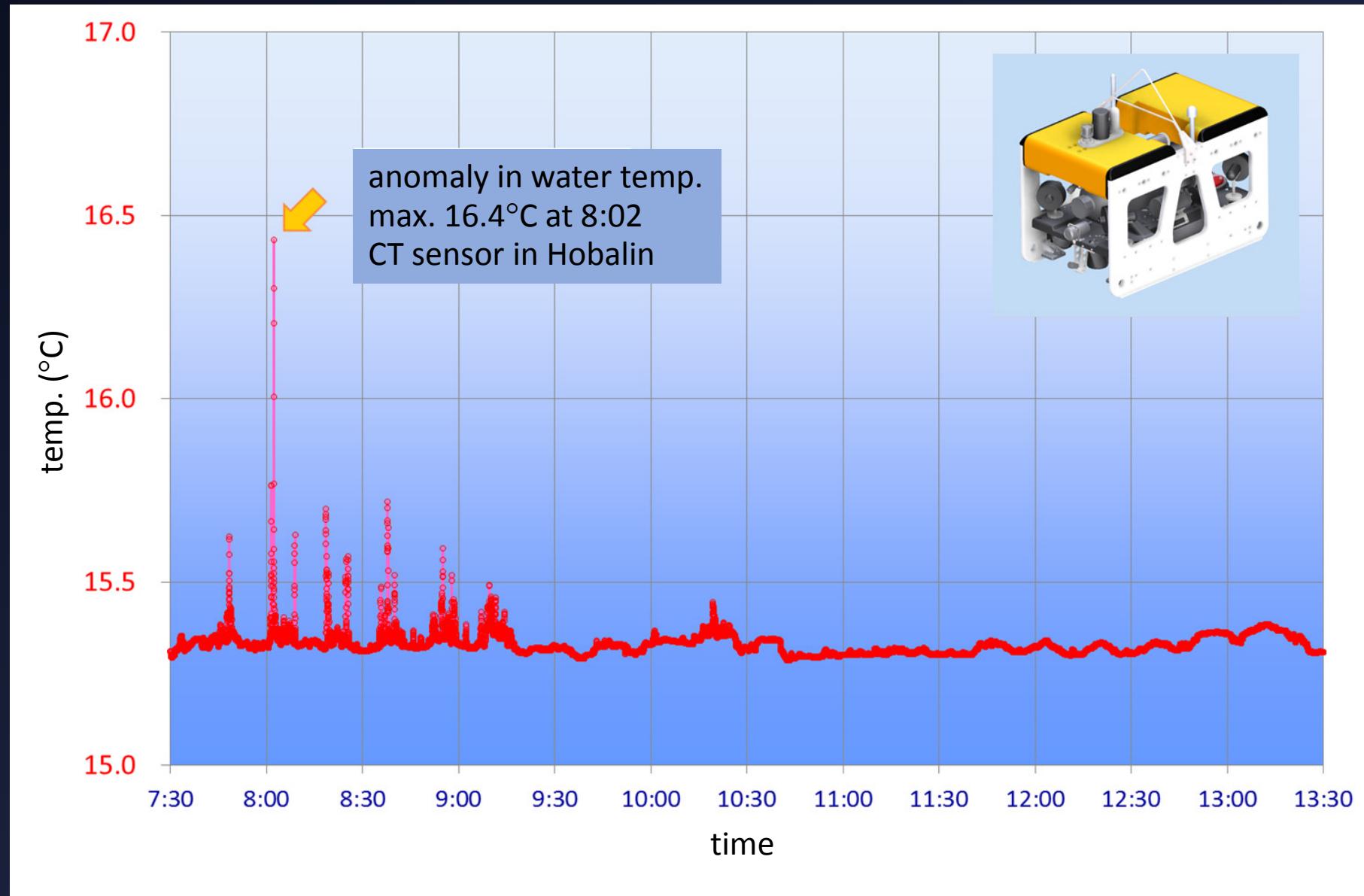


new: 2 m meshed, C-AUV#02

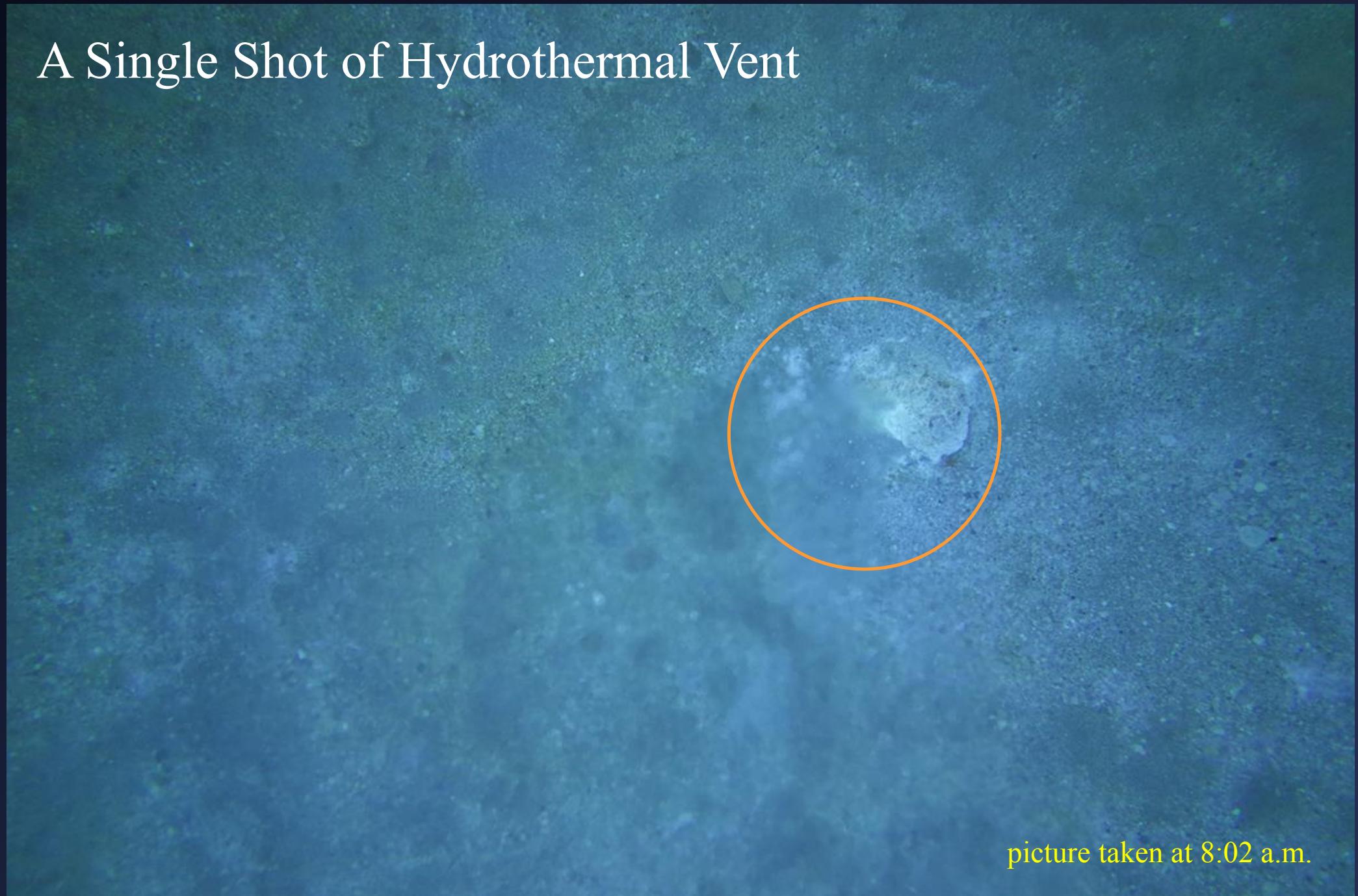
- Sign of Hydrothermal Activity: Plumes in Acoustic Images



- Sign of Hydrothermal Activity: Temperature and Photo Images



A Single Shot of Hydrothermal Vent

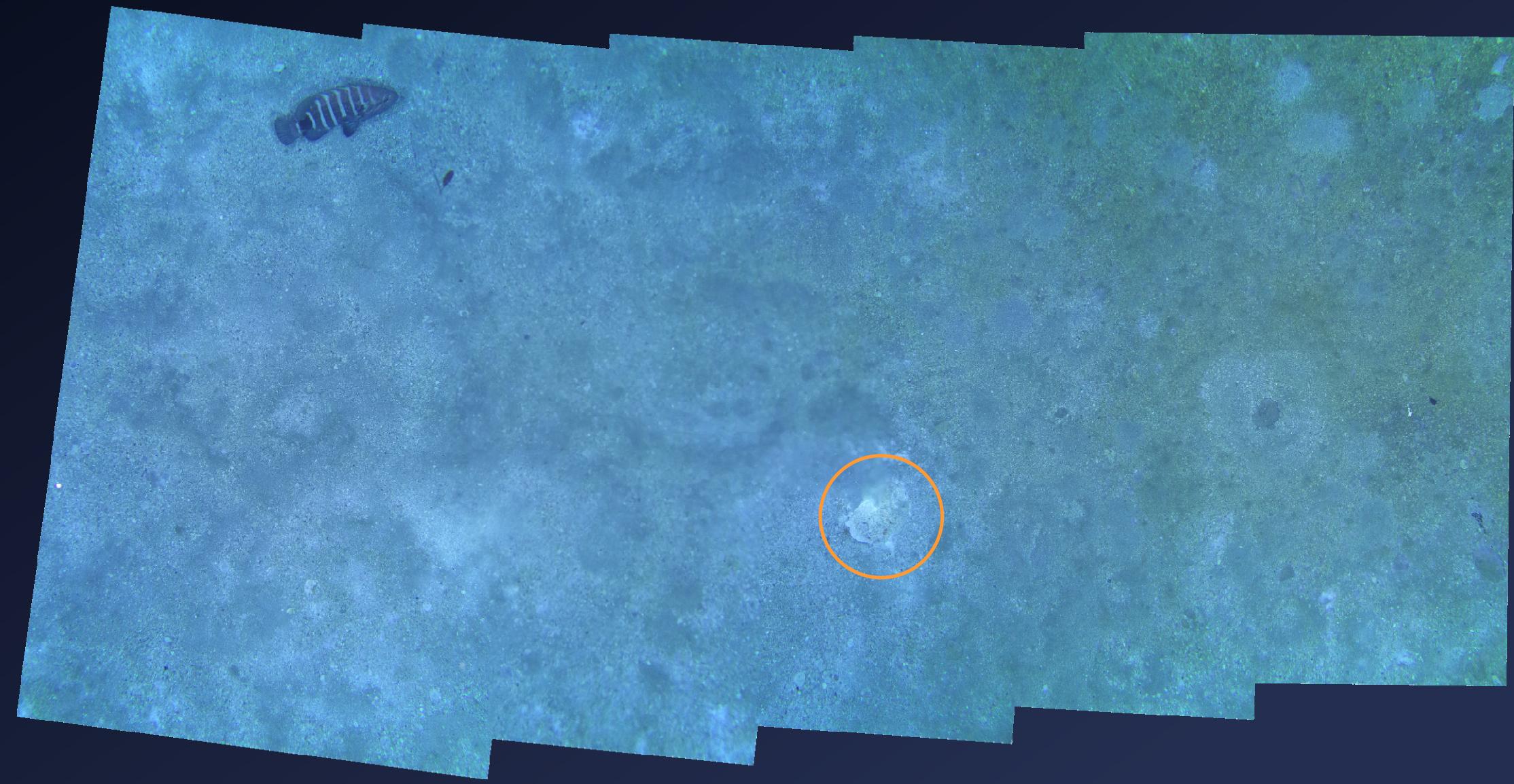


picture taken at 8:02 a.m.

A Single Shot of Hydrothermal Vent (Enlarged)

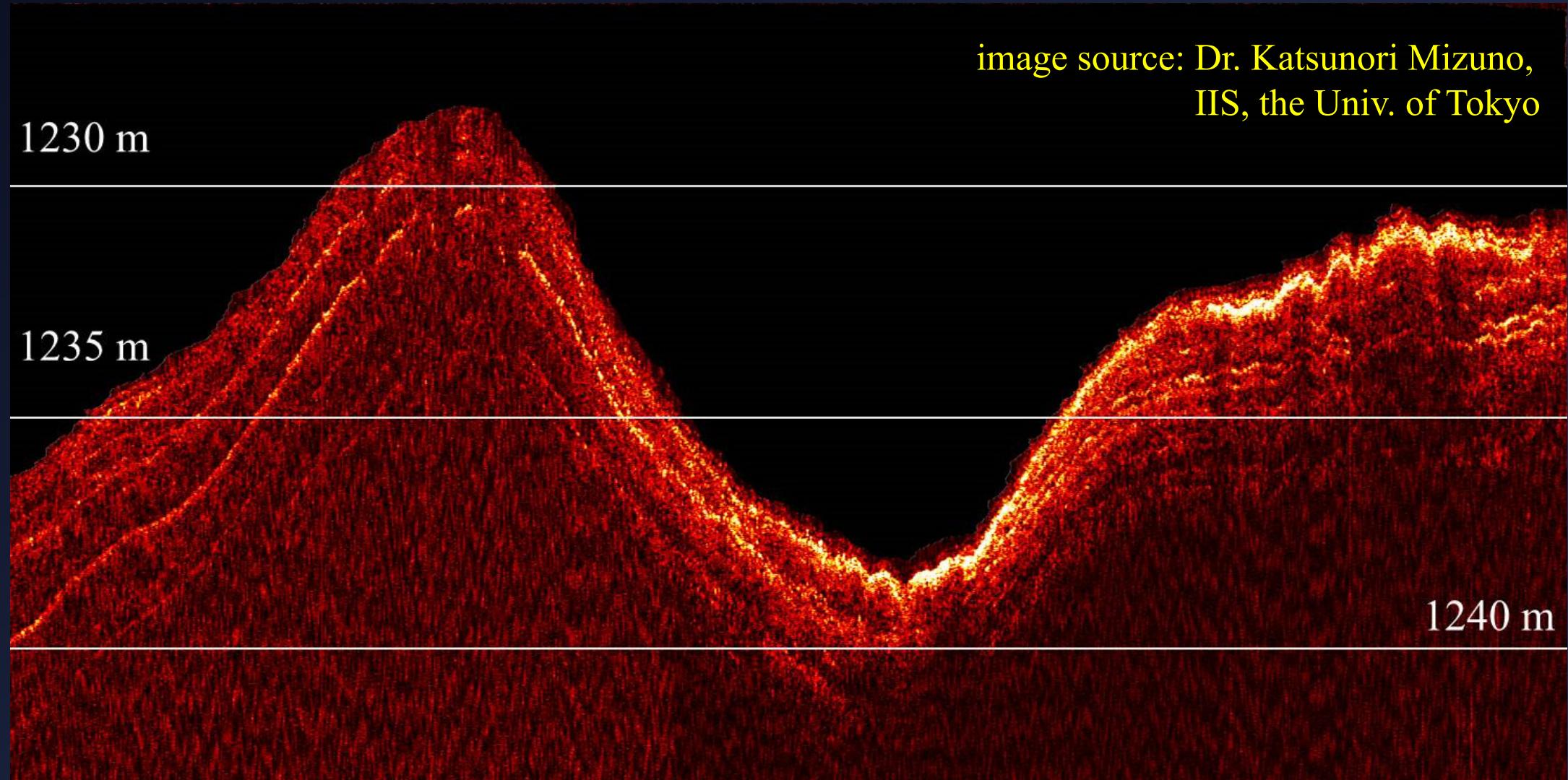


Mosaicked Bottom Image



Sub-Bottom Profiling

- sub-bottom layers of Hatsushima Offing visualized by PSBP(Parametric SBP) installed in C-AUV#01



Conclusions and Future Works

- Simultaneous Deployment and Operation of Multiple AUVs
 - *2 C-AUVs, 1 H-AUV*
 - *controlled by an ASV*
 - *surveyed hydrothermal activities*
- Future Works
 - Advanced Navigation
 - Increased No. of Vehicles: *4 AUVs in 2017*



*Practical Mission
achieved by a Pure
Unmanned Survey Unit*

ACKNOWLEDGMENTS

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